

BUBNOV-GALERKIN METHOD FOR SOLVING DIFFERENTIAL EQUATIONS

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Annotation: The bend is called flat or straight if the plane of action of the load passes through the main central axis of inertia of the section. As a result of the construction, a plot of the distribution of the bending moment for each section of the beam was obtained, from which the greatest value is visible. Changes in normal and tangential stresses along the length of the beam depend on the values of transverse forces and bending moments. This study allows you to gain skills that will be used in project practice.

Keywords: beams, axis, plane, curved axis, rod, beam, structure, cross sections.

The Bubnov-Galerkin method is one of the methods for solving differential equations, which was developed in the early 20th century by Russian mathematicians Sergei Bubnov and Boris Galerkin. This method is one of the most effective and widely used methods for solving differential equations.

The Bubnov-Galerkin method is based on the representation of the solution of a differential equation in the form of a linear combination of functions that are selected in such a way as to satisfy the initial and boundary conditions. These functions are called basis functions.

To apply the Bubnov-Galerkin method, it is necessary to select the basis functions that will be used to represent the solution of the differential equation. Usually, such functions are chosen as basis functions that satisfy certain conditions, for example, orthogonality or compactness.

Then it is necessary to substitute the representation of the solution into the original differential equation and obtain a system of equations for the coefficients of the linear combination. This system of equations is solved numerically, and the coefficients obtained are used to find a solution to the differential equation.

The Bubnov-Galerkin method is a numerical method for solving differential equations, which is based on the representation of the solution as a linear combination of a certain basis of functions. In this case, the basis can be functions describing the shape of the plate, for example, the functions of sines and cosines

Steps of the Bubnov-Galerkin method for calculating a pivotally fixed rectangular plate:

1. Set the basis of the functions that we will use to approximate the solution. In this case, you can use the sine and cosine functions.
2. Write down the equation describing the behavior of the plate. In this case, it is the equation of vibrations of an elastic plate.
3. Substitute the basis functions into the equation and obtain a system of equations for the coefficients of decomposition of the solution by the basis.
4. Solve a system of equations for coefficients.

5. Substitute the coefficients found in the expression for the solution and get a numerical solution to the problem.

The Bubnov-Galerkin method makes it possible to obtain an approximate solution of a differential equation with high accuracy using a finite number of basis functions. However, to achieve high accuracy, it is required to use a large number of basic functions, which can lead to computational difficulties.

The Bubnov-Galerkin method is based on a theorem from the theory of general Fourier series. Let $\{U_i\}$ be a complete system of functions (with nonzero norm) orthogonal on the segment $[a,b]$. If a continuous function $f(x)$ is also orthogonal on the segment $[a,b]$ to all functions $U_i(x)$, i.e.

$$\int_a^b f(x) \varphi_i(x) dx = 0$$

then the function $f(x)$ is identically zero for $a \leq x \leq b$.

According to the Galerkin method, the solution is also sought in the form:

$$Y = \varphi_0(x) + \sum_{i=1}^n a_i \varphi_i(x) \quad (1)$$

Where satisfies $\varphi_0(x)$ inhomogeneous (non-zero) boundary conditions:

$$\varphi_0(a) = A, \quad \varphi_0(b) = B \quad (2)$$

And the function $(i=1,2,\dots,n)$ satisfies (zero) boundary conditions.

$$\varphi_i(a) = \varphi_i(b) = 0 \quad (3)$$

It is obvious that the function (1) will satisfy the boundary conditions (2), (3) for any values of constant coefficients.

Substituting (1) into a differential equation, for example into the equation: $y''=f(x)$, we obtain a residual:

$$\varphi_0''(x) + \sum_{i=1}^n a_i \varphi_i''(x) - f(x) \neq 0 \quad (4)$$

According to the Galerkin method, we require that the discrepancy (4) be orthogonal to the basic ("coordinate") functions $\varphi_k(x)$:

$$\int_a^b [\varphi_0''(x) + \sum_{i=1}^n a_i \varphi_i''(x)] \varphi_k(x) dx = 0 \quad (k=1,2,\dots,n)$$

Or

$$\int_a^b \sum_{i=1}^n a_i \varphi_i''(x) \varphi_k(x) dx = \int_a^b [-\varphi_0''(x) + f(x)] \varphi_k(x) dx$$

Or in expanded form:

$$y''(x) + xy'(x) + y(x) = 2x \quad (5)$$

Satisfying the boundary conditions:

$$y(0)=1, y(1)=0 \quad (6)$$

We are looking for a solution to the equation in the form:

$$y = (1-x) + a_1(1-x) + a_2x^2(1-x) + a_3x^3(1-x) + \dots \quad (7)$$

$x(1-x) = \varphi_1$; $x^2(1-x) = \varphi_2$; $x^3(1-x) = \varphi_3$ satisfying the boundary conditions (6): $y(0)=1$, $y(1)=0$ for any . Substituting (7) into (5), we get the discrepancy:

$$y'' : [a_1(-2) + a_2(2-3*2x) + a_3(3*2x-4*3x^2)] +$$

$$xy' : [-x + a_1x(1-2x) + a_2x(2x-3x^2) + a_3x(3x^2-4x^3)]$$

$$y : [(1-x) + a_1(x-x^2) + a_2(x^2-x^3) + a_3(x^3-x^4)] =$$

$$(1-2x) + a_1(-2+x-2x^2+x-x^2) + a_2(2-6x+2x^2-3x^3+x^2-x^3) + a_3(6x-12x^2+3x^3-4x^4 +$$

$$+ x^3 - x^4) - 2x =$$

$$(1-2x) + a_1(-3x^2+2x-2) + a_2(-4x^3+3x^2-6x+2) + a_3(-5x^4+4x^3-12x^2+6x) - 2x \neq 0 \quad (8)$$

Multiplying (8) sequentially by $x(1-x) = \varphi_1$; $x^2(1-x) = \varphi_2$; $x^3(1-x) = \varphi_3$

and equating the resulting expressions to zero, we get after integration from 0 to 1:

$$a_1 \int_0^1 (x-x^2)(-3x^2+2x-2)dx + a_2 \int_0^1 (x-x^2)(-4x^3+3x^2-6x+2)dx + a_3 \int_0^1 (x-x^2)(-5x^4+4x^3-12x^2+6x)dx$$

$$a_1 \int_0^1 (3x^4-5x^3+4x^2-2x)dx + a_2 \int_0^1 (4x^5-7x^4+9x^3-8x^2+2x)dx + a_3 \int_0^1 (5x^6-9x^5+16x^4-18x^3+6x)dx =$$

$$-\int_0^1 (x-x^2)(1-4x)dx = -\int_0^1 (x-5x^2+4x^3)dx = \left(\frac{x^2}{2} - \frac{5x^3}{3} + \frac{4x^4}{4}\right) \Big|_0^1 = \frac{1}{6}$$

or

$$a_1 \left(-\frac{19}{60}\right) + a_2 \left(-\frac{3}{20}\right) + a_3 \left(-\frac{6}{70}\right) = \frac{1}{6}$$

Where

$$(x-x^2) = \varphi_1$$

Finally we have:

$$133a_1 + 63a_2 + 36a_3 = -70$$

$$140a_1 + 108a_2 + 79a_3 = -98$$

$$264a_1 + 252a_2 + 211a_3 = -210$$

Solving a system of algebraic equations, we obtain:

$$a_1 = -0.209; a_2 = -0.7894; a_3 = 0.209$$

Thus, the solution of equation (7) is found:

$$y = (1 - x)(1 - 0.209x - 0.7894x^2 + 0.209x^3)$$

The Bubnov-Galerkin method has many applications in various fields of science and technology. It is widely used in mathematical modeling, in the theory of elasticity, in hydrodynamics, in the theory of thermal conductivity and many other fields.

One of the advantages of the Bubnov-Galerkin method is its versatility and ease of use. It allows you to solve differential equations of varying complexity and can be adapted to solve specific problems

Thus, the Bubnov-Galerkin method is one of the most effective and widely used methods for solving differential equations. It has many applications in various fields of science and technology and is an important tool for solving complex problems.

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